

<b>COURSE NUMBER:</b> Ve460		<b>COURSE TITLE:</b> Control Systems Analysis and Design	
<b>CREDIT:</b> 4		<b>PREREQUISITES:</b> Ve216	
<b>TEXTBOOKS/REQUIRED MATERIAL:</b> Automatic Control Systems, 8th Edition, 2003, ISBN: 978-0-471-13476-3, by B. C. Kuo and F. Golnaraghi		<b>PREPARED BY:</b> Jun Zhang <b>DATE OF PREPARATION:</b> Oct, 2013 <b>DATE OF UC APPROVAL:</b>	
<b>INSTRUCTOR(S):</b> Jun Zhang		<b>SCIENCE/DESIGN:</b> n/a	
<b>CATALOG DESCRIPTION:</b> Basic techniques for analysis and design of controllers applicable in any industry (e.g. automotive, aerospace, computer, communication, chemical, bioengineering, power, etc.) are discussed. Both time- and frequency-domain methods are covered. Root locus, Nyquist and Bode plot-based techniques are outlined. Computer-based experiment and discussion sessions are included in the course.		<b>COURSE TOPICS:</b> 1. Introduction 2. Mathematical foundation 3. Block diagrams and signal flow graphs 4. Modeling of systems 5. Stability 6. Time-domain response 7. Root locus 8. Frequency-domain analysis 9. Design techniques 10. State variable analysis	
<b>COURSE STRUCTURE/SCHEDULE:</b> Lecture: two times per week			
<b>COURSE OBJECTIVES</b> [Course Outcomes in brackets]	<ol style="list-style-type: none"> <li>To teach students basic concepts of steady-state and transient analysis of linear feedback systems; [1]</li> <li>To teach students basic concepts of robustness of linear feedback systems; [2]</li> <li>To teach students techniques and CAD tools for designing linear feedback control systems; [3, 4, 5, 6]</li> <li>To stimulate student interest in control applications, &amp; to prepare them for industry &amp; graduate study [1-6]</li> </ol>		
<b>COURSE OUTCOMES</b> [Program Outcomes in brackets]	<p>After completing Ve460, students should be able to:</p> <ol style="list-style-type: none"> <li>Ability to design a controller so that a feedback systems meets steady-state and transient specs; [a, c]</li> <li>Ability to design a controller so that a feedback systems meets robustness specs; [a, c]</li> <li>Ability to recognize feedback problems that are fundamentally difficult;</li> <li>Ability to use root locus, Nyquist and Bode techniques to modify properties of a control system; [a]</li> <li>Ability to identify and evaluate design tradeoffs among specs such as rise time and robustness; [a, e]</li> <li>Ability to use CAD tools (Matlab) for analysis and design of control systems. [a, k]</li> </ol>		
<b>ASSESSMENT TOOLS</b> [Course Outcomes in brackets]	<p>Homework: 30 % (including course participation) Midterm: 30 % Final: 35 % Attendance: 5 %</p>		